



**02 - 05.1** <sub>10.05.GB</sub>

# Control valves G 45 ...





### Kv coefficient calculation

Calculation itself is carried out with respect to conditions of regulating circuit and operating medium according to equations mentioned below. Control valve must be designed to be able to regulate maximal flow quantity at given operating conditions. At the same time it is necessary to check whether minimal flow quantity can be even regulated or not.

Because of eventual minus tolerance 10% of Kv. against Kvs and requirement for possible regulation within range of maximal flow (decrement and increase of flow), producer recommends to select Kvs value higher than maximal operating Kv value:

$$Kvs = 1.2 \div 1.3 Kv$$

It is necessary to take into account to which extent  $Q_{\mbox{\tiny max}}$  involve "precautionary additions" that could result in valve oversizing.

### Relations of Kv calculation

		Pressure drop	Pressure drop
		$p_2 > p_1/2$	$\Delta p \ge p_1/2$
		$\Delta p < p_1/2$	$p_2 \leq p_1/2$
Kv =	Liquid	-Q 100-1	$\frac{\rho_1}{\Delta p}$
	Gas	$\frac{Q_n}{5141}\sqrt{\frac{\rho_n.T_1}{\Delta p.p_2}}$	$\frac{2.Q_{\scriptscriptstyle n}}{5141.p_{\scriptscriptstyle 1}}\sqrt{\rho_{\scriptscriptstyle n}.T_{\scriptscriptstyle 1}}$
	Superh. steam	$\frac{Q_{_{m}}}{100}\sqrt{\frac{v_{_{2}}}{\Delta p}}$	$\frac{Q_{\scriptscriptstyle m}}{100}\sqrt{\frac{2v}{p_{\scriptscriptstyle 1}}}$
	Sat. steam	$\frac{Q_{m}}{100}\sqrt{\frac{v_{2}.x}{\Delta p}}$	$\frac{Q_m}{100}\sqrt{\frac{2v.x}{p_1}}$

## Above critical flow of vapours and gases

When pressure ratio is above critical ( $p_2/p_1 < 0.54$ ), speed of flow reaches acoustic velocity at the narrowest section. This event can cause higher level of noisiness and then it is convenient to use a throttling system ensuring low noisiness (multi-step pressure reduction, damping orifice plate at outlet).

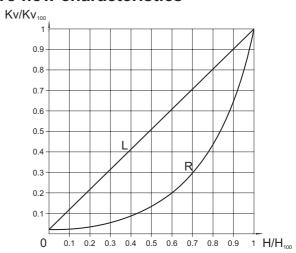
### Cavitation

Cavitation is a phenomenon when there are steam bubbles creating and vanishing in shocks - generally at the narrowest section of flowing due to local pressure drop. This event expressively cuts down service life of inner parts and can result in creation of unpleasant vibrations and noisiness. In control valves it can happen on condition that

$$(p_1 - p_2) \ge 0.6 (p_1 - p_3)$$

Valve differential pressure should be set the way so that neither any undesired pressure drop causing cavitation can occur, nor liquid-steam(wet steam) mixture can create. Otherwise it must be taken into account when calculating Kv value. If the creation of cavitation still threatens, it is necessary to use a multi-step pressure reduction.

### Valve flow characteristics



L - linear characteristic

 $Kv/Kv_{100} = 0.0183 + 0.9817 \cdot (H/H_{100})$ 

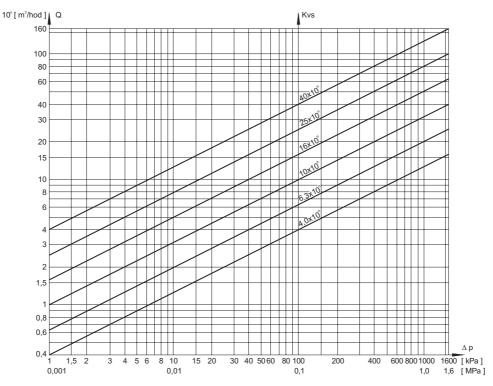
R - equal-percentage characteristic (4-percentage)  $Kv/Kv_{100} = 0.0183 \cdot E^{(4 \cdot H/H_{100})}$ 

### **Dimensions and units**

Marking	Unit	Name of dimension
Kv	m³/hour	Flow coefficient under conditions of units of flow
Kv <sub>100</sub>	m³/hour	Flow coefficient at nominal stroke
Kvs	m³/hour	Valve nominal flow coefficient
Q	m³/hour	Flow rate in operating conditions (T <sub>1</sub> , p <sub>1</sub> )
$\overline{Q}_n$	Nm³/hour	Flow rate in normal conditions (0 °C, 0.101 MPa)
$Q_{m}$	kg/hour	Flow rate in operating conditions (T <sub>1</sub> , p <sub>1</sub> )
$p_1$	MPa	Upstream absolute pressure
$\overline{p_{\scriptscriptstyle 2}}$	MPa	Downstream absolute pressure
p <sub>s</sub>	MPa	Absolute pressure of saturated steam at given temperature (T, )
Δρ	MPa	Valve differential pressure ( $\Delta p = p_1 - p_2$ )
$\overline{\rho_1}$	kg/m³	Process medium density in operating conditions (T <sub>1</sub> , p <sub>1</sub> )
$\rho_n$	kg/Nm³	Gas density in normal conditions (0 °C, 0.101 MPa)
$V_2$	m³/kg	Specific volume of steam when temperature T <sub>1</sub> and pressure p <sub>2</sub>
V	m³/kg	Specific volume of steam when temperature T <sub>1</sub> and pressure p <sub>1</sub> /2
T <sub>1</sub>	K	Absolute temperature at valve inlet (T <sub>1</sub> = 273 + t <sub>1</sub> )
х	1	Proportionate weight volume of saturated steam in wet steam



# Diagram for the valve Kvs value specification according to the required flow rate of water Q and the valve differential pressure $\Delta p$



The diagram serves to specify the valve Kvs value regarding to the required flow rate of water at a given differential pressure. It can be also used for finding out the differential pressure value of the existing valve in behaviour with the flow rate. The diagram apllies to water with the density of 1000 kg/m³.

For the value Q =  $q \cdot 10^\circ$ , it is necessary to calculate with Kvs =  $k \cdot 10^\circ$ . Example: water flow rate of 16  $\cdot 10^\circ$  = 1,6 m³/hour corresponds to Kv = 2,5 = 25. 10 when differential pressure 40kPa.

# Valve complete specification No. for ordering G 45

		X XX	XXX	- X XXX	/ XXX	- XXX
1. Valve	Control valve	G				
2. Series	Lever control valve, double-seated	45				
<ol><li>Flow direction</li></ol>	Straight - through		1			
4. Connection	Flanged		1			
	Weld ends		2			
5. Actuating	Adjusted for remote control		5			
6. Material	Alloy steel 1.7357			2		
	Carbon steel 1.0619			5		
7. Nominal pressure PN	Acc. to the valve execution			XXX		
8. Max. operating temp.° C	Acc. to the valve execution				XXX	
9. Nominal size DN	Acc. to the valve execution					XXX





G 45 115 ...

### Lever control valves DN 150 to 400, PN 16 to 100

### **Description**

The valve is double-seated, lever-actuated designed to be actuated with an electric or a pneumatic actuator possibly with an electric or a hydraulic cylinder. It is also possible to use linear or rotative actuator. Its control plug is always designed according to the parameters specified in the order and according to the required type of flow characteristic.

The valves can be delivered with lever actuators of the following producer: ZPA Pečky - Modact MPS, Modact Control MPS and Modact Variant MPR, possibly with linear actuators ZPA Pečky, Regada Prešov and rotative actuators Auma or Schiebel. The connection stem between the valve lever and the actuator is not a subject of the delivery unless it is ordered.

### **Application**

The valve serves as a control, reducing or by-pass element with indirect, possilbly with direct actuating. The max. permissible operating pressures acc. to EN 12 516-1 see page 14 of this catalogue. The intention to use the valve for higher temperatures must be agreed upon with the producer. The control valve's proper function depends on the sizing and execution of the control station, therefore the valve design and its specification is recommended to be carried out together with the producer.

#### Process media

The valves are designed to regulate the flow and pressure of liquids, possibly of vapours and gases e.g. water, steam and other media compatible with material of material of the valve inner parts. The valve max. differential pressure value is 4,0 MPa with respect to the pressure nominal and concrete conditions of operation (ratio  $p_1$  /  $p_2$ , creation of cavitation, above critical flow etc.)

#### Installation

The valve can be piped only in a horizontal pipeline with vertically positioned stem and the valve lever positioned up above the valve body. The medium flow direction shall corespond to the arrows indiciated on the valve body. The lever is mounted on the right side from the medium flow direction unless it is required otherwise.

### **Technical data**

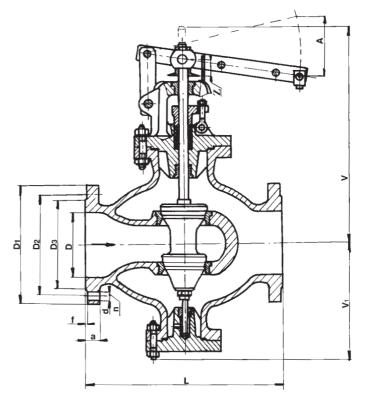
Series	G 45 115 240	G 45 115 2100	G 45 115 516	G 45 115 525	G 45 115 540	G 45 115 564	G 45 115 5100	
Type of valve		Lever control valve, flanged, straight-through,double-seated						
Nominal size range	200	150	200, 300, 400	200, 400	200, 400	150	150	
Nominal pressure	40	100	16	25	40	64	100	
Body material	Alloy ste	el 1.7357	Carbon steel 1.0619					
Operating temp. range		550°C	-20 to 400°C					
Connection*	ČSN 13 1213	ČSN 13 1215	ČSN 13 1211	ČSN 13 1212	ČSN 13 1213	ČSN 13 1214	ČSN 13 1215	
Type of trim			seat / sea	it cage - conto	ured plug			
Flow characteristic		Linear, e	qual-percenta	ge acc. to ČSI	N EN 60 534-1	1 (4/1997)		
Flow area range Fs [cm²]	17 - 200	10 - 110	17 - 408	17 - 408	17 - 408	10 - 110	10 - 110	
Kvs values range	76,5 - 900	45 - 495	76,5 - 1836	76,5 - 1836	76,5 - 1836	45 - 495	45 - 495	
Leakage rate			Class III acc	to ČSN EN 1	349 (5/2001)			

<sup>\*)</sup> mentioned ČSN are from 1963. After the agreement with the producer, it is possible to make the connection acc. to ČSN 13 1060 (7/1995) or ČSN EN 1092-1 (4/2002).



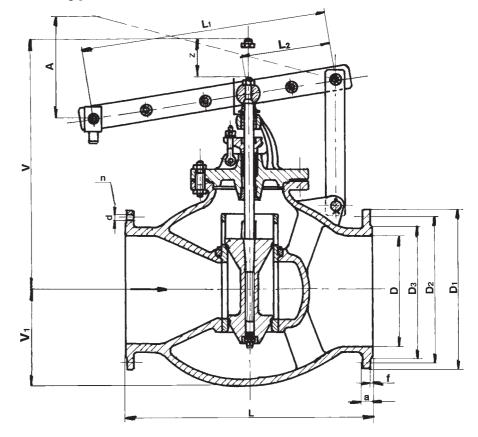
# Dimensions and weights for the type G 45 115 DN 150 to 300

Туре		r 2	G 450 110 010	G 45 115 525	G 45 115 240 G 45 115 540	G 45 115 564	G 45 115 2100 G 45 115 5100
DN	[mm]	200	300	200	200	150	150
D	[mm]	200	300	200	200	150	150
L	[mm]	600	850	600	600	600	600
~V	[mm]	680	930	680	680	660	660
~V <sub>1</sub>	[mm]	360	500	360	360	360	360
D <sub>1</sub>	[mm]	335	460	360	375	340	350
$\frac{D_1}{D_2}$	[mm]	295	410	310	320	280	290
$D_3$	[mm]	268	378	278	280	240	250
Α	[mm]	270	270	270	270	280	280
f	[mm]	3	4	3	3	3	3
а	[mm]	24	28	30	34	36	44
d	[mm]	23	27	27	30	33	33
n	[mm]	12	12	12	12	8	12
Fs	[cm <sup>2</sup> ]	17-200	40-250	17-200	17-200	10-110	10-110
Kvs	[m³/h]	76,5-900	180-1125	76,5-900	76,5-900	45-495	45-495
m	[kg]	380	600	380	380	400	420



# Dimensions and weights for the type G 45 115 DN 400

Туре		G 45 115 516	G 45 115 525	G 45 115 540
DN	[mm]	400	400	400
$\begin{array}{c c} D \\ \hline L \\ L_1 \\ \hline L_2 \\ \hline \sim V \\ \hline \sim V_1 \\ \hline D_1 \\ \hline D_2 \\ \hline D_3 \\ \hline A \\ \hline f \end{array}$	[mm]	400	400	400
L	[mm]	900	900	900
L,	[mm]	856	856	856
L2	[mm]	306	306	306
~V	[mm]	910	910	910
~V <sub>1</sub>	[mm]	360	360	360
D <sub>1</sub>	[mm]	580	610	655
$D_2$	[mm]	525	550	585
$D_3$	[mm]	490	505	535
Α	[mm]	280	280	280
f	[mm]	4	4	4
а	[mm]	50	50	50
a d	[mm]	30	33	40
n	[mm]	16	16	16
Fs	[cm <sup>2</sup> ]	80-408	80-408	80-408
Kvs	[m³/h]	360-1100	360-1100	360-1100
m	[kg]	1023	1023	1023







G 45 125 ...

Control valves DN 300, PN 40

### **Description**

The valve is double-seat, lever-actuated, designed to be actuated with an electric actuator, possibly with an electric or a hydraulic cylinder. It is also possible to use linear or rotative actuator. Its control plug is always designed according to the parameters specified in the order and according to the required type of flow characteristic.he valves can be delivered with lever actuators of the following producer: ZPA Pečky - Modact MPS, Modact Control MPS and Modact Variant MPR, possibly with linear actuators ZPA Pečky, Regada Prešov and rotative actuators Auma or Schiebel. The connection stem between the valve's lever and the actuator is not a subject of the delivery unless it is ordered.

### **Application**

The valve serves as a control, reduction or a by-pass valve with indirect or direct actuating. The max. permissible operating pressures acc. to EN 12 516-1 see page 14 of this catalogue. The intention to use the valve for higher temperatures must be agreed upon with the producer. The control valve proper function depends on the sizing and execution of the control station, therefore the valve design and its specification is recommended to be carried out together with the producer.

### **Process media**

The valves are designed to regulate the flow and pressure of liquids, possibly of vapours and gases e.g. water, steam and other media compatible with material of the valve inner parts. The valve max. differential pressure value is 4,0 MPa with respect to the pressure nominal and concrete conditions of operation (ratio  $p_1/p_2$ , creation of cavitation, above critical flow etc.)

#### Installation

The valve can be piped only in a horizontal pipeline with vertically positioned stem and the valve lever positioned up above the valve body. The medium flow direction shall corespond to the arrows indiciated on the valve body. The lever is mounted on the right side from the medium flow direction unless it is required otherwise.

#### Technical data

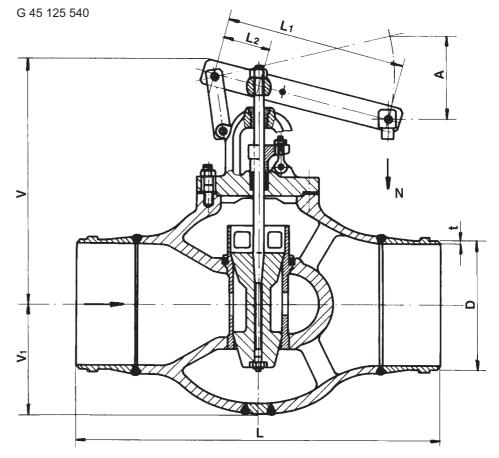
Series	G 45 125 240	G 45 125 540			
Type of valve	Control valve, flanged, straig	ght-through, double-seated			
Nominal size	30	0			
Nominal pressure	40	)			
Body material	Alloy steel 1.7357	Carbon steel 1.0619			
Operating temperature range	-20 to 450°C	-20 to 400°C			
Connection *	ČSN 13 1070 (1984)				
Type of trim	Seat - contoured plug				
Flow characteristic	Linear, equal-percentage acc. to ČSN EN 60 534-1 (4/1997)				
Flow area range Fs [cm²]	40 - 175				
Kvs values range	180 - 787,5				
Leakage rate	Class III acc. to ČSN EN 1349 (5/2001)				

<sup>\*)</sup> After the agreement with the producer, it is possible to make the connection acc. to the valid ČSN 13 1075 (3/1991) or ČSN EN 12 627 (8/2000)

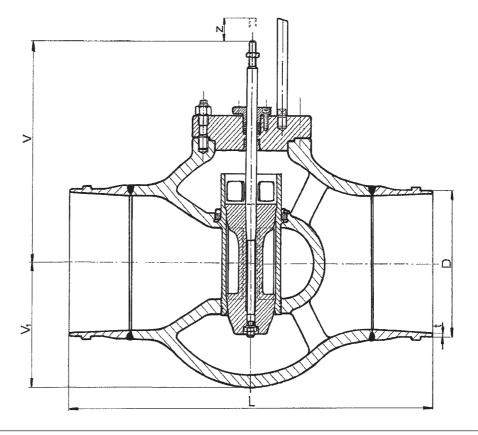


# Dimensions and weights for G 45 125 DN 300

Туре		G 45 125 540	G 45 125 240
DN	[mm]	300	300
D	[mm]	324	324
L	[mm]	900	900
~V	[mm]	660	494
~V <sub>1</sub>	[mm]	265	265
t	[mm]	8	8
L,	[mm]	440	
L <sub>2</sub>	[mm]	110	
A	[mm]	240	
$ \begin{array}{c c} \hline D\\ \hline L\\ \sim V\\ \sim V_1\\ \hline t\\ \hline L_1\\ \hline L_2\\ \hline A\\ z\\ \hline Fs \end{array} $	[mm]		60
Fs	[cm <sup>2</sup> ]	40-175	40-175
Kvs	[m³/h]	180-787,5	180-787,5
m	[kg]	375	300



G 45 125 240







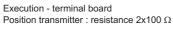
**52 262 52 263** 52 264

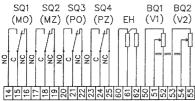
# **Electric actuators Modact MPS** and Modact MPS Control **ZPA Pečky**

### **Technical data**

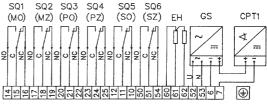
Туре	Modact MPS Modact MPS	Control			
Voltage	3 x 230 V / 400 V <u>+</u> 6%				
Frequency	50 Hz				
Motor power	See specification table				
Control	2 - position or 3 - position control				
Torgue range	160 to 1250 Nm				
Travel range	60° to 160°				
Enclosure	IP 55				
Process media max. temperature	Acc. to used valve				
Ambient temperature range	-25 to 55°C				
Ambient humidity range	10 - 100 % with condensation				
Weight	max. 120 kg	max. 120 kg			

### Wiring diagram of actuator Modact MPS



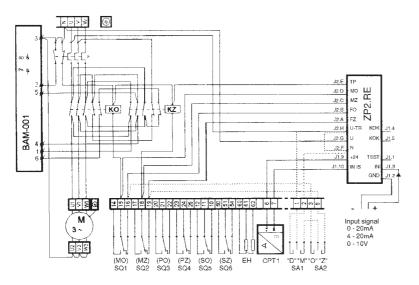






# Wiring diagram of actuator Modact MPS Control

With current transmitter, built-in contactor combination, heat reley, positioner ZP2.RE and dynamic brake BAM-001.



SQ1(MO) torgue switch in "opening" direction SQ2 (MZ) torgue switch in "closing" direction limit switch in "opening" direction limit switch in "closing" direction signalisation switch in "opening" direction SQ3 (PO) SQ5 (PZ) SQ4 (SO) SQ6 (SZ) signalisation switch in "closing" direction heaters 2 x TR 551 10k/A EΗ capacity position transmitter CPT1/A4 - 20 mA CPT1 BAM-001 dynamic brake contactor in "opening" direction KO ΚZ contactor in "closing" direction F heat reley SA1 control switch "local -remote" SA2 switch "open - close" BQ1, BQ2 position transmitter  $2 \times 100 \Omega$ ZP2.RE micro-computer positioner power supply source for current GS ransmitter 230V/24V M1~ one-phase motor М3~ inductive, three-phase motor motor capacitor C T mains transformer S Z terminal board

plug "KBNS"



XXX7

## **Specification for actuators Modact MPS and Modact MPS Control**

Basic equipment: 1 electromotor

2 torgue switches MO, MZ

2 heaters

2 signalisation switches SO, SZ - for actuators with CPT 1/A

and actuators without any transmitter

	2 limit switches PO, PZ
Basic technical data:	

	Tripping		Electromotor			0:1 6:11:	\\/a:ala4	Specification No	
Туре	torgue setting range [Nm]	time [s/90°]	Motor power [W]	Current to motor In [A]	Current to motor Iz [A]	Oil filling	Weight [kg]	Basic	Additional
MPS 32/16		16							XX1X
MPS 32/32	160 220	32	180	0,57	1,82	2.4	70	52 262	XX2X
MPS 32/63	160 - 320	63	100	0,57	1,02	3,4	70	32 202	XX3X
MPS 32/120		120							XX4X
MPS 63/16		16	370	1,05	3,25				XX1X
MPS 63/32	220 620	32				10	120	52 263	XX2X
MPS 63/63	320 - 630	63	180	0,57	1,82	10	120	52 203	XX3X
MPS 63/120		120							XX4X
MPS 125/16		16							XX1X
MPS 125/32	200 4050	32	370	1,05	3,25	10	400	E0 004	XX2X
MPS 125/63	630 - 1250	63				10	120	52 264	XX3X
MPS 125/120		120	180	0,57	1,82				XX4X

Execution, electric connection:

via terminal board						
With conector KBSN (for Modact MPS only)			7XXX			
		60°	X1XX			
Operating travel -mechanically connected with controlled	with lever and flange with stops	90°	X2XX			
	will level and hande will slobs					

element 120° X3XX 160 X4XX Resistance position transmitter 2 x 100  $\Omega$ XXX1 XXX0

Additional equipment for Execution without any position transmitter actuators Modact MPS Current pos. transmitter CPT 1/A 4-20 mA with built-in power supply generator Current pos. transmitter CPT 1/A 4-20 mA wo. built-in power supply generator

XXX9 Completely equipped with Without positioner, with brake Without positioner and brake Additional equipment for BAM and reversible contactors BAM, with reversible contactors positioner and brake BAM actuators Modact MPS Control with BMO without BMO with BMO without BMO with BMO without BMO Without position trasnmitter **XXXC** XXXL XXXG **XXXR** Resistance position transmitter 2 x 100  $\Omega$ XXXD **XXXM XXXH** XXXS CPT 1/A 4-20 mA with built-in power supply generator XXXE XXXN XXXJ XXXT XXXA CPT 1/A 4-20 mA without built-in power supply generator XXXB XXXF XXXP XXXK XXXU

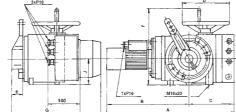
### **Dimensions of actuator Modact MPS and Modact MPS Control**

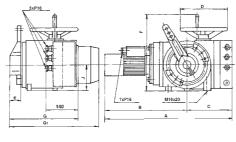
Modact MPS

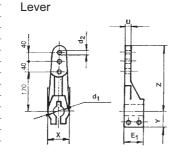
	52 262	52 263	52 264				
Α	620	712	731				
A B C D E E 1 F G G 1 J K L M N O S T U X Y Z d d d 1	386	460	479				
С	234	25	52				
D	□200	□2	50				
E	62	8	2				
Εı	60	8	0				
F	346	42	20				
G	340	44	15				
G <sub>1</sub>	456	56	52				
J	120	14	15				
K	70	10	00				
L	90	110					
М	140	20	00				
Ν	41	6	0				
0	□14	<b>1</b>					
S	56	7	0				
<u>T</u>	4	7	7				
U	25	3	0				
X	65	8	0				
Υ	41	5	5				
Z	273	27	78				
d	□40 h 8	□50	h 8				
$d_1$	□40 H 7	□50	H 7				
d <sub>2</sub>	3x□20H8	3x□2	25H8				
b	12 P9	16	P9				
h	8	10					

43,8

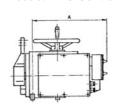
35





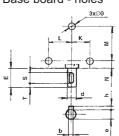


Modact MPS Control



	52 262	52 263	52 264				
Α	370	44	10				
В	250	275					

#### Base board - holes







52 222 52 223

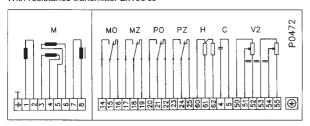
# Electric actuators Modact Variant MPR ZPA Pečky

### **Technical data**

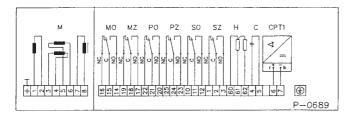
Type	Modact Variant MPR
Voltage	230 V ± 6%
Frequency	50 Hz
Motor power	50 W
Control	Continuous
Torgue range	250 to 4000 Nm
Travel range	60° to 160°
Enclosure	IP 55
Process media max. temperature	Acc. to used valve
Ambient temperature range	-25 to 55 ℃
Ambient humidity range	10 - 100 % with condensation
Weight	max. 282 kg

## Wiring diagram of actuator

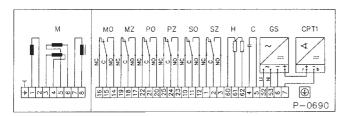
Execution - terminal board With resistance transmitter 2x100  $\Omega$ 



With current transmitter CPT1/A, without built-in power supply source



With current transmitter CPT1/A with built-in power supply source



MO MZ PO PZ SO SZ H	torgue switch in "opening" direction torgue switch for "closing" direction limit switch in "opening" direction limit switch in "closing" direction signalisation switch in "opening" direction signalisation switch in "closing" direction heaters
CPT1	capacity position transmitter CPT1/A4 - 20 mA
V2	resistance position transmitter 2 x 100 $\Omega$
GS	power supply source for current transmitter 230V/24V
M	induction, two-phase motor
С	capacitor
S	terminal board
Z	plug "KBNS"

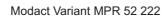


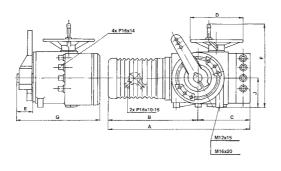
# **Specification of actuator Modact Variant MPR**

Nominal		Max.	Running time		Electromoto	r	Oil	\A/-:I-4	Specification No.	
Type	torgue [Nm]	torgue [N/m]	range [sec/90°]	[W]	[ µF ]	BF/ŘF [A]	filling [ kg ]	Weight [ kg ]	Basic	Additional
MPR 25-40	250-400	1400	10-19							XX0X
MPR 40-63	400-630	1750	14-30	50	8	0,6/0,6	4,4	104	52 222	XX1X
MPR 63-100	630-1000	2650	30-55							XX2X
MPR 100-200	1000-2000	4550	50-80							XX0X
MPR 160-300	1600-3000	5950	73-138	50	8	0,6/0,6	4,4	282	52 223	XX1X
MPR 250-400	2500-4000	8940	130-195							XX2X
Execution, e	electrical co	onnection:								
Via termina	l board									6XXX
With conect	or KBSN									7XXX
				60° for 5	2 222		67,5° for	52 223		X1XX
				90° for 5	2 222		90° for	X2XX		
Operating to	ravel			120° for 5	2 222		112,5° for	X3XX		
				160° for 5	2 222		157° for	X4XX		
				90° for 5	2 222; dired	ct connection.				X5XX
			Execution	without po	sition trans	smitter				XXX1
Additional e	lootrio	V2	Position re	sistance tr	ansmitter 2	2 x 100 Ω				XXX0
equipment	lectric	CPT1+GS	Position cu	irrent trans	mitter CP	Г 1/А 4-20 і	mA with built	-in power sup	ply generator	XXX7
		CPT1	Position cu	irrent trans	smitter CP	Γ 1/A 4-20 ι	mA wo. built-	in power sup	52 222	XXX9
Stem		with single	stem		For	export only				XXXX/3
Sterri	with double stem For export only			XXXX/4						

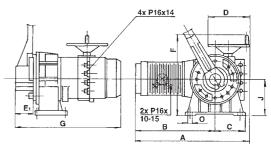
# **Dimensions of actuator Modact Variant MPR**

	52 222	52 223
Α	782	793
В	517	548
С	265	220
D	□250	□300
Е	85	123
E <sub>1</sub>	80	120
F	420	120 560
G	555	750
J	145	260
K	145 100 110 200	185
L	110	
M	200	200
Ν	57	33
0	□18	□22
Р	40	55
R	170	400
S	70	180
Т	170 70 7	11
U	30	36
Χ	80	130
Υ	55	80
Z	278	490
d	□50 h 8	□90 h 8
A B C D E E 1 F G J K L M N O P R S T U X Y Z d d d 1	□50 h 8 □40 h 7	□90 h 8 □90 h 7
$d_2$	3x□25H8	3x=40h8
b h	16 P9	25 P9
h	10	14
e	43,8	81,3

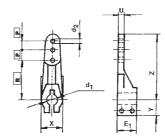




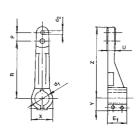
Modact Variant MPR 52 223



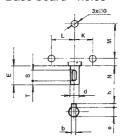
Lever



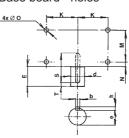
Lever



Base board - holes

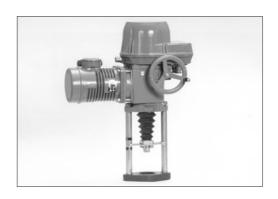


Base board - holes





52 420



## **Electric actuators Modact MTR** ZPA Křižík Prešov

### **Technical data**

<del>_</del>	AA I IAATO
Туре	Modact MTR
Voltage	230 V
Frequency	50 / 60 Hz
Motor power	16 or 25 W
Control	3 - pos. c. (in connection with NOTREP positioner - continuous)
Nominal force	6.3, 10, 16, 25 kN
Travel	12,5 to 100 mm
Enclosure	IP 54 ( IP 65 on request)
Process medium max. temperature	Acc. to used valve
Ambient temperature range	-25 to 55°C
Ambient humidity limit	90 % (tropical version: 100 % with condensation)
Weight	27 to 31 kg

# Wiring diagram of actuator

Execution - terminal board

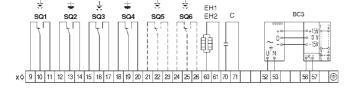
Wiring diagram with resistance transmitter 2x100  $\boldsymbol{\Omega}$ 



Wiring diagram with capacity transmitter 4 - 20 mA (with its source)



Wiring diagram with inductive transmitter (0) 4 - 20 mA; 0 - 5 mA



SQ1 (MO) power switch in "opening" direction SQ2 (MZ) power switch in "closing" direction SQ3 (PO) limit switch in "opening" direction
SQ4 (PZ) limit switch in "closing" direction
SQ5 (SO) signalisation switch in "opening" direction
SQ6 (SZ) signalisation switch in "closing" direction

EH1, EH2 heaters 2 x TR 551 10k/A

BC2 resistance position transmitter  $2 \times 100 \Omega$ 

BC3 inductive position transmitter (0) 4 - 20 mA; 0 - 5 mA BC4 capacity position transmitter 4 - 20 mA

capacitor С Χ terminal board

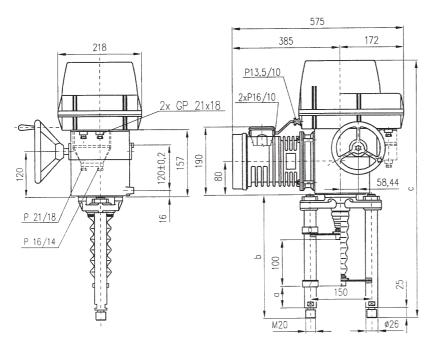


# **Specification of Modact MTR**

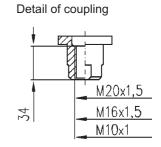
Electric actuator MTR, linear 52 420.								X	Х	Χ	Χ	/	X	X		
Execution CX - as standard (-25°C to 55°C), connection via terminal board																
Execution T2 - tropical (-25°C to 55°C, 100% condensation), connection via terminal board  16										6						
											2					
25											3					
Travel	Travel [mm] 32										4					
40											5					
	63										6					
Linear	unit with acme	threa	d Tr 26x5													
											0					
ina ford	4000	atin	2500 - 4000	ina	50	ag agi	60 - 50	ma for	13000			1				
Nominal linear force <sup>)</sup>	10000	Operating linera force	6300 - 10000	Nominal speed	32	Operating speed	38 - 32	laxi era	30000			2				
∠ <u>⊆</u>	6300	0. <u>⊆</u>	4000 - 6300	_	50	0	60 - 50	_ = _	20000			3				
Linear	unit with ball b	olt K 2	5x5													
	16000		10000 - 16000		32	Operating speed	38 - 32	Maximal linear force <sup>2)</sup>	39000			4				
Nominal linear force <sup>1)</sup>	10000	മെ	6300 - 10000	_	50		60 - 50		30000			5				
iina forc	25000	Operating linear force	10000 - 25000	Nominal speed	32		38 - 32		55000			6				
dor	16000	per ear	10000 - 16000		50		60 - 50		40000			7				
<u> </u>	10000	0.≦	6300 - 10000	_	63	0	75 - 63		39000			8				
	6300		4000 - 6300		100		120 - 100		29000			9				
			Without transmitter										0			
				2 x 100 Ω									1			
			Resistance	1 x 2000 Ω								2				
			resistance	2 x 20	$\Omega$ 00								3			
Transr	nitter			1 x 20	+ Ω 00	1x100	Ω						4			
			Inductive [mA]	(0) 4 -	20								5			
			inductive [mA]	0 - 5									6			
Capacity [mA] 4 - 20 (with its generator)							ator)						7			
			Capacity [IIIA]	4 - 20	(withou	ıt its ge	nerator)						8			
				Colum	nns UNI	_									7	_
Specia	al mechanical c	connec	tion	Colum	Columns Č. Třebová										8	
				2 sign	alisatio	n switc	hes SQ5, SQ6	i								Р

- Switching-off linear force is set to nominal value with tolerance of + 30 %.
   Measured linear force with motor running into short-circuit state with voltage of 230 V on position controller.

### **Dimensions of Modact MTR**



		th ac		With ball bolt				
Columns ČT	130	378	707	130	400	729		
Columns UNL	74	320	649	74	344	673		





# Maximal permissible overpressures acc. to EN 12 516-1 [MPa]

Material	PN								
		200	250	300	350	400	450	500	550
Cast steel 1.0619	16	1.14	1.04	0.94	0.88	0.84			
	25	1.78	1.62	1.47	1.37	1.32			
	40	2.84	2.60	2.35	2.19	2.11			
	63	4.48	4.09	3.71	3.45	3.33			
	100	7.11	6.50	5.89	5.48	5.28			
Alloy steel 1.7357	40	3.74	3.57	3.33	3.09	2.89	2.67	5.57	2.21
	100	9.34	8.93	8.32	7.71	7.22	6.67	8.90	3.50

Notes:



N	otos	
IV	ores	